



RPI Header

Mainly used for providing power to the RPI, drawing 3.3V from the RPI for the HAT, and exchanging data over UART.

Secondary Out

Header used to connect the secondary system to the main system. Connects UART, GND, and BATT for monitoring on the main board. NOTE: UART is crossed over on main board.

Microcontroller (MCU)

Collects and distributes bike data between RPI systems using UART to communicate with RPIs. Can be programmed and debugged either by UART through the RPI or USB. SWD header also added for programming without USB support.

RPI it is mounted to connects by UART1, the other on UART3. There is a button to reset specifically the MCU.

There are a few controlled status LEDs.

Telemetry

nRF24L01 used for telemetry to chase vehicle. Only data is transferred, no voice.

Sec. Input

Connections for secondary board to connect to main board.

Wheels

Both wheels have an MLX90614 sensor to monitor brake disk temperature, the rear has an IR reflectometer used as an optical encoder for distance and speed. These sensors provide data over I2C and a digital line respectively.

GPS

GPS is used primarily as a backup source for distance and speed information but location can also be recorded during the run.

Power Input

Power from LiFePO4 batteries is fed through a reverse polarity protection circuit, then to the monitor power pads and the 5V regulator.

MH-Z19 (CO2)

Digital CO2 sensor that measures up to 2000ppm using infrared. Outputs level using PWM.

Sensor is placed near the riders' heads.

DHT11

Digital temperature and humidity sensor used to derive ambient air conditions for performance calculations.

Sensor is placed near the air intake.

HAT for RPIs in TITAN for the WHPSC 2022
Provides 5V for RPI in addition to gathering data from TITAN
Only one STM32 is needed in the system on the main board
Secondary board only has power systems and the header to main

Title: TITAN HAT

HPVDT	Date: 2022-08-16	Rev: 3.1
KiCad E.D.A. kicad 6.0.2+dfsg-1	Size: USLetter	Sheet: 1/1